

# An algorithm to invert matrix based on LU decomposition to apply in reactor core analyses

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The analysis of a nuclear reactor, be it for power production, radioisotope production, or even for research, is always preceded by the determination of the neutron flux distribution  $\Psi$  in the reactor core, both in space, energy, angular direction, and also in the time variable. Using operators to describe the neutron distribution we have:

$$\Theta\Psi = S \quad (1)$$

where,  $\Theta$  is an operator describing neutron interactions and spatial dependence, and  $S$  represents an external source.

Analytical solution is impractical for Eq.(1). Usually, solutions are based on so-called numerical methods. For that, the operator equation is discretized spatially in such way that we always have an equation system represented by a matrix like this:

$$\underline{\underline{M}}\Psi = \underline{\underline{S}} \quad (2)$$

This system can be analyzed, according to its nature, as well- or ill-conditioned [1]. The first leads to a numerical solution, dependent only on an acceptable error. The second one does not lead to a solution. This matrix condition number,  $\kappa(\underline{\underline{M}})$ , is defined by:

$$\kappa(\underline{\underline{M}}) = \frac{\|\underline{\underline{M}}\|}{\|\underline{\underline{M}}^{-1}\|} \quad (3)$$

where,  $\|X\|$  represents the norm of matrix  $X$ . In Eq.(3), well-conditioned system has  $\kappa(\underline{\underline{M}}) \approx 1$ . On the hand, large one is ill-one. For determining  $\underline{\underline{M}}^{-1}$ , the usual method is to use the well-known adjoint matrix  $adj(\underline{\underline{M}})$  and associated determinant  $|\underline{\underline{M}}|$ .

$$\underline{\underline{M}}^{-1} = \frac{1}{|\underline{\underline{M}}|} adj(\underline{\underline{M}}) \quad (4)$$

However, in reactor core calculations, when we consider space and energy, this leads to a very expensive matrix calculations.

In this work, we have developed an algorithm to calculate the  $\|\underline{\underline{M}}^{-1}\|$ , based on  $\underline{\underline{L}}\underline{\underline{U}}$  decomposition. Here  $\underline{\underline{L}}$  is Lower, with unit at principal diagonal, and  $\underline{\underline{U}}$  is Upper matrices.

$$\underline{\underline{M}} = \underline{\underline{L}}\underline{\underline{U}} \quad (5)$$

$$\underline{\underline{M}}^{-1} = \underline{\underline{U}}^{-1}\underline{\underline{L}}^{-1} \quad (6)$$

We have applied this matrix methodology using a finite difference for a discretization to a 1D diffusion operator

$$\Theta\Psi|_i = -\frac{\partial^2\Psi}{\partial x^2}|_i \approx \frac{1}{(\Delta x)^2}(-\Psi_{i-1} + 2\Psi_i - \Psi_{i+1}) \quad (7)$$

For four points, the matrices are:

$$\underline{\underline{M}} = \begin{bmatrix} 2 & -1 & 0 & 0 \\ -1 & 2 & -1 & 0 \\ 0 & -1 & 2 & -1 \\ 0 & 0 & -1 & 2 \end{bmatrix}$$

$$\underline{\underline{L}} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1/2 & 1 & 0 & 0 \\ 0 & -2/3 & 1 & 0 \\ 0 & 0 & -3/4 & 1 \end{bmatrix} \quad \underline{\underline{L}}^{-1} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1/2 & 1 & 0 & 0 \\ 1/3 & 2/3 & 1 & 0 \\ 1/4 & 1/2 & 3/4 & 1 \end{bmatrix}$$

$$\underline{\underline{U}} = \begin{bmatrix} 2 & -1 & 0 & 0 \\ 0 & 3/2 & -1 & 0 \\ 0 & 0 & 4/3 & -1 \\ 0 & 0 & 0 & 5/4 \end{bmatrix} \quad \underline{\underline{U}}^{-1} = \begin{bmatrix} 1/2 & 1/3 & 1/4 & 1/5 \\ 0 & 2/3 & 1/2 & 2/5 \\ 0 & 0 & 3/4 & 3/5 \\ 0 & 0 & 0 & 4/5 \end{bmatrix}$$

$$\underline{\underline{M}}^{-1} = \frac{1}{5} \begin{bmatrix} 4 & 3 & 2 & 1 \\ 3 & 6 & 4 & 2 \\ 2 & 4 & 6 & 3 \\ 1 & 2 & 3 & 4 \end{bmatrix}$$

Condition numbers are exhitad at Tab 1.

**Table 1: Condition numbers and norms.**

	$\ \underline{\underline{M}}\ $	$\ \underline{\underline{M}}^{-1}\ $	$\kappa(\underline{\underline{M}})$
$L_1$	4.000	4.500	18;00
$L_2$	5.292	3.919	20.74
$L_\infty$	4.000	4.500	18.00

## Reference

[1] KUO, S.S., Computer Applications of Numerical Methods, Addison-Wesley, 1972.